

# MATH327: Statistical Physics

Monday, 15 May 2023

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## Something to consider

Suppose we want to *approximately* compute expectation values

$$\langle O \rangle = \sum_{i=1}^M O_i p_i = \frac{1}{Z} \sum_{i=1}^M O_i e^{-\beta E_i} = \frac{\sum_{i=1}^M O_i e^{-\beta E_i}}{\sum_{i=1}^M e^{-\beta E_i}}$$

How many of the system's micro-states do we really need to analyze?

Plan

Mean-field approx for Ising model  
Numerical methods (more broadly applicable)

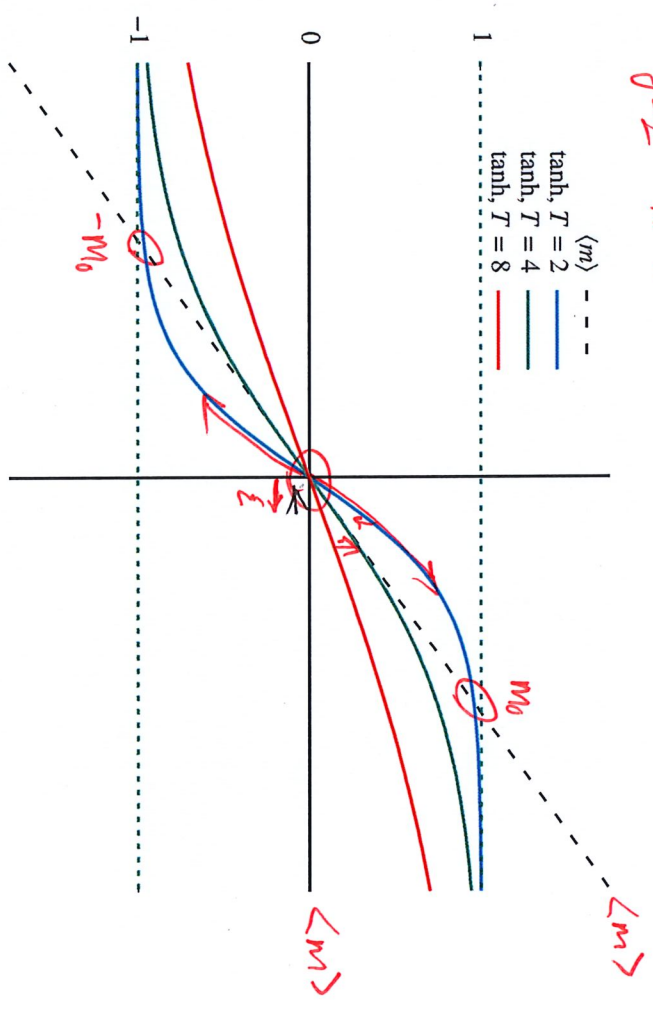
Recap

$$E = - \sum_{\langle ij \rangle} J_{ij} S_i S_j - H \sum_n S_n \rightarrow -d \cdot N \langle m \rangle^2 - \underbrace{(2d \langle m \rangle + H)}_{H_{\text{eff}}} \sum_n S_n$$

Assuming small average fluctuations  
→ non-interacting w/ effective magnetic field  
involving mean spin & 2d n.n.'s

Self-consistency condition  $\langle m \rangle = \tanh(\beta(2d \langle m \rangle + H))$   
H=0 & low temperature → three solutions  $\langle m \rangle = 0$  (unstable)  
 $\langle m \rangle = \pm m_0 \neq 0$

$\beta=2$   $H=0$



Another way to see  $\langle m \rangle = 0$  instability

Plot  $\tanh(2\beta d \langle m \rangle) - \langle m \rangle$  to find roots

Positive  $\rightarrow \langle m \rangle$  too small

Negative  $\rightarrow \langle m \rangle$  too large

Conclude  $\langle m \rangle = 0$  unstable for low temperature ( $\mu = 0$ )

Mean-field approx  $\rightarrow$  ordered/disordered like full Ising model

When does  $\langle m \rangle = 0$  become unstable?

(If phase trans., this will be  $T_c$ )

Need  $\tanh' \langle m \rangle$  for  $\langle m \rangle = \epsilon > 0 \rightarrow$  slope of  $\tanh > 1$  at  $\langle m \rangle = 0$

$$\begin{aligned} \left. \frac{d}{d\langle m \rangle} \tanh(2\beta d \langle m \rangle) \right|_{\langle m \rangle = 0} &= \left. \frac{d}{d\langle m \rangle} \left( 2\beta d \langle m \rangle + \mathcal{O}(\langle m \rangle^3) \right) \right|_{\langle m \rangle = 0} \\ &= 2\beta d = 1 \\ T_c &= \frac{1}{\beta_c} = 2d \end{aligned}$$

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Is there a phase transition (w/discontinuity)?

Consider  $T \approx T_c \rightarrow 0 < |\langle m \rangle| \ll 1$

$$\langle m \rangle = \tanh(2\beta d \langle m \rangle) = 2\beta d \langle m \rangle - \frac{1}{3} (2\beta d \langle m \rangle)^3 + \mathcal{O}(\langle m \rangle^5)$$

$\downarrow \frac{T_c}{T}$

$$\frac{1}{3} \left( \frac{T_c}{T} \right)^3 \langle m \rangle^2 = \frac{T_c}{T} - 1$$

$$\langle m \rangle^2 = 3 \left( \frac{T}{T_c} \right)^3 \left( \frac{T_c}{T} - 1 \right) = 3 \left( \frac{T}{T_c} \right)^2 \left( 1 - \frac{T}{T_c} \right)$$

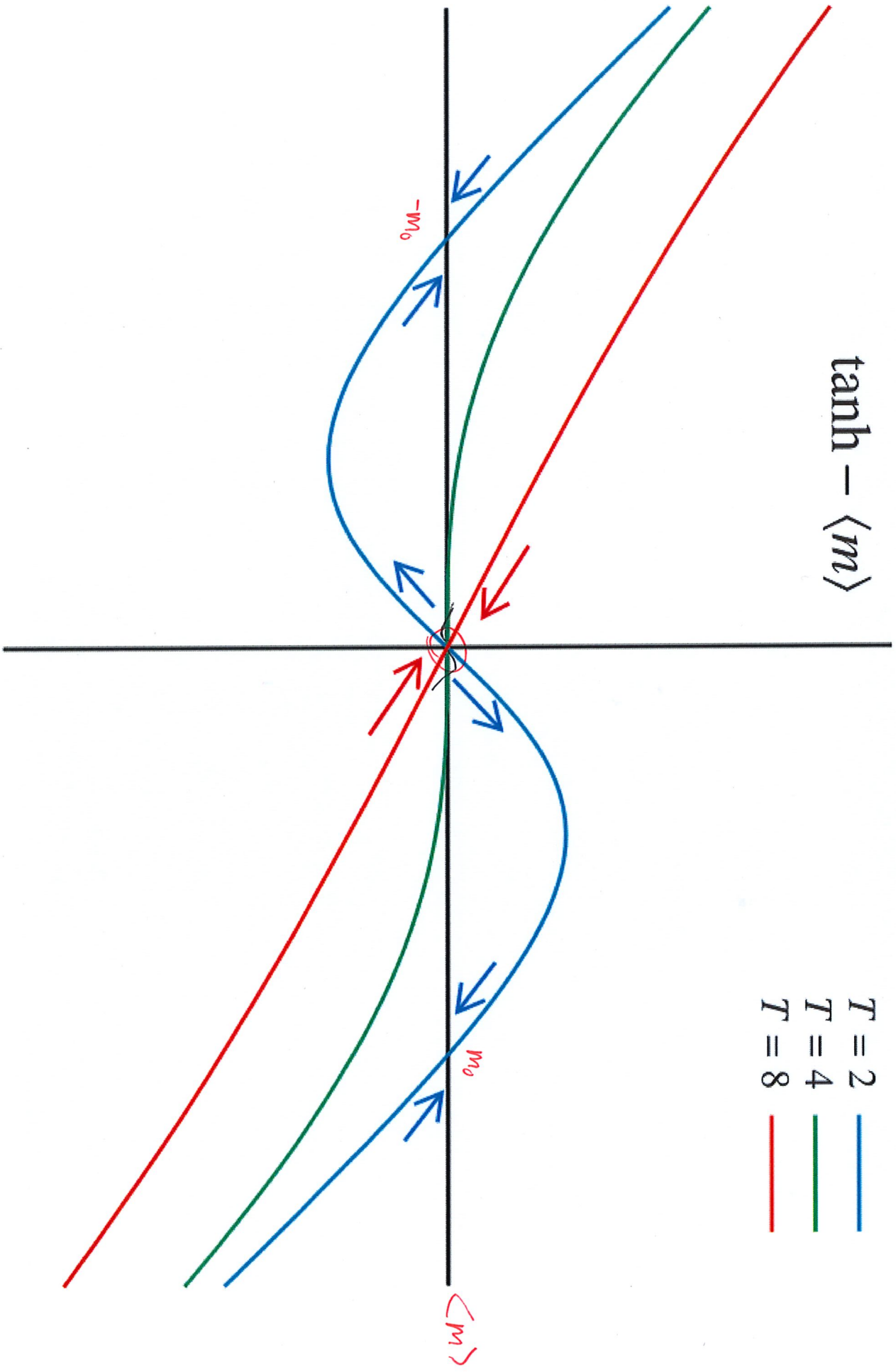
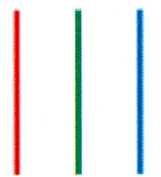
Approximating  $\left( \frac{T}{T_c} \right)^2 \approx 1$

$$\langle m \rangle = \pm \sqrt{3} \left( 1 - \frac{T}{T_c} \right)^{1/2} = \pm \sqrt{3} \left( \frac{T_c - T}{T_c} \right)^{1/2}$$

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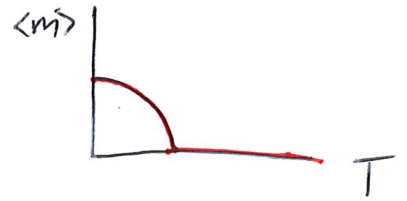
$\tanh - \langle m \rangle$

$T = 2$   
 $T = 4$   
 $T = 8$



So magnetization is continuous at  $T = T_c$

$$\langle m \rangle \propto \begin{cases} (T_c - T)^{1/2} & \text{for } T \lesssim T_c \\ 0 & \text{for } T \gtrsim T_c \end{cases}$$



But  $\frac{d\langle m \rangle}{dT} \propto \frac{1}{(T_c - T)^{1/2}}$  for  $T \lesssim T_c$  diverges as  $T \rightarrow T_c$  from below

→ 2nd-order phase trans. predicted by mean-field approx.

General result when  $\langle m \rangle \propto (T_c - T)^b$  with non-integer critical exponent  $b = 1/2$

Many phase trans. have same sets of critical exponents  
→ universality emergent large-scale behaviour near crit. pt. independent of microscopic details

Mean-field predictions ( $H=0$ ) 2nd-order PT  $b = 1/2$   
 $T_c = 2d$

Are these predictions correct?

$d=1$ : No phase transition (supplement) X

$d=2$ : 2nd-order phase trans. (Onsager 1944) ✓

$$T_c = \frac{z}{\log(1+\sqrt{z})} \approx 2.27 \quad (\text{supplement}) \quad \text{MF } T_c = 4 \text{ off by } \sim 2\times$$

$$b = 1/8, \quad \text{MF off by } 4\times$$

$d=3$ : Numerical analyses → 2nd order,  $T_c \approx 4.5$  (vs. 6)  
 $b \approx 0.32$

$d \geq 4$ :  $b = 1/2$  ✓

$$T_c \rightarrow 2d \text{ as } d \rightarrow \infty$$

MF becomes exact sol'n when  $2d \rightarrow \infty$   
( $2d$  n.n.'s to average over)

# Numerical analyses

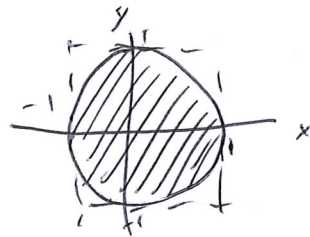
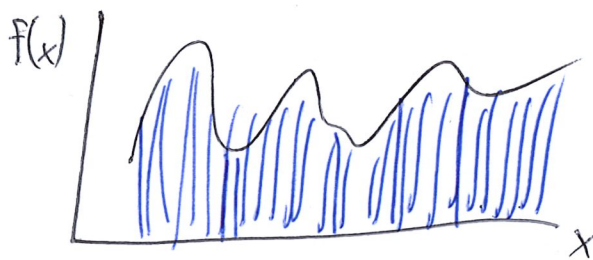
Needed for Ising model with  $d > 2$   
and most interacting systems

How? Recall  $\sim 500,000 \times$  age of universe  
to evaluate all  $\sim 10^{32}$  terms in  $10 \times 10$  Ising model  
part. func.

Sample small subset of micro-states  
to approximate  $\langle O \rangle$

(Pseudo-)randomly  $\rightarrow$  "Monte Carlo" methods

Example: Compute integral by ~~not~~ evaluating integrand  
at random points



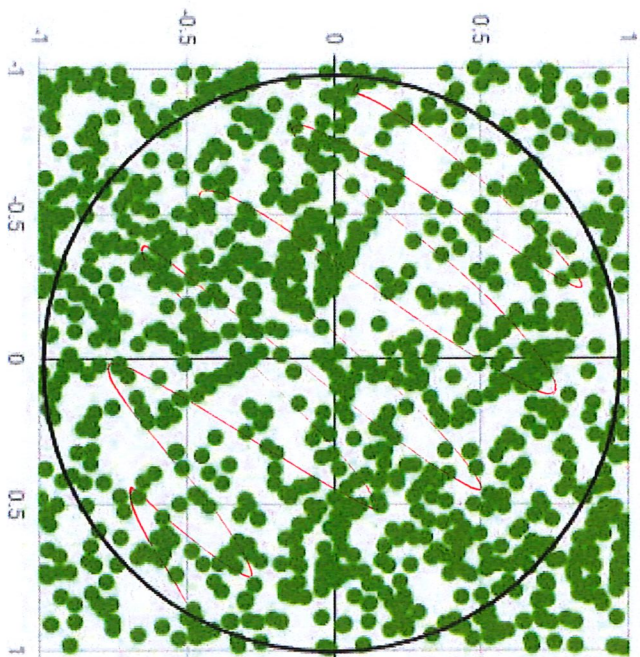
$$\int_{-1}^1 dx \int_{-1}^1 dy H(1 - \{x^2 + y^2\}) = \text{area of disk w/ radius } r=1 \rightarrow \pi$$

$$H(r) = \begin{cases} 1 & \text{for } r \geq 0 \\ 0 & \text{for } r < 0 \end{cases}$$

Monte Carlo integration most useful for high-dimensional integrals  
--- like part. func. for interacting statistical systems  $w/N \gg 1$

Can only consider very small fraction of micro-state  
ratio fraction  $\sim \frac{\text{length of computation}}{\text{many times age of universe}} \ll 1$

How can this give reliable approximations?



$$\text{fraction} = \frac{\pi}{4}$$

Return ~~to~~ to Ising model

High-T limit  $\rightarrow$  all micro-states equally probable  
 $\langle O \rangle$  determined by degeneracies

Large degeneracy more likely to be sampled  
... could be okay

Low-T limit  $\rightarrow$   $\langle O \rangle$  determined by ground state  
other micro-states' contributions suppressed  $\sim e^{-\beta E_i}$

Solution: Sample  $w_i$  with probability  $p_i \propto e^{-\beta E_i}$   
without knowing  $p_i$  distribution

$\rightarrow$  Importance sampling algorithms use pseudo-randomness  
Find important  $w_i$  w/large  $p_i$  without bias

Example: MRRTT algorithm (1953)

Start from any micro-state

Make a pseudo-random change  $\rightarrow \Delta E$

$P_{\text{accept}} = \min \{ 1, \exp(-\beta \Delta E) \}$  otherwise reject

$\rightarrow$  New micro-state (possibly ~~unchanged~~)

Repeat!

Ising  
spin config.  
select  $s_j$  & flip it

Sequence of micro-states is "Markov chain"

(each  $w_i$  based on previous one, no memory!)

$$\frac{P(A \rightarrow B)}{P(B \rightarrow A)} = \frac{\min \{ 1, e^{-\beta(E_B - E_A)} \}}{\min \{ 1, e^{-\beta(E_A - E_B)} \}} = e^{-\beta(E_B - E_A)} = \frac{e^{-\beta E_B}}{e^{-\beta E_A}} \checkmark$$



To avoid bias, Markov chain must (in principle) be able to reach any micro-state from any <sup>other</sup> micro-state  
→ Ergodicity depending on specific system and how state is updated

Statistical uncertainty  $\propto \frac{1}{\sqrt{S}}$   
number of samples

These are ongoing research question  
~~we~~ which we've reached ~~at~~ just a few months  
after starting w/probability foundations!